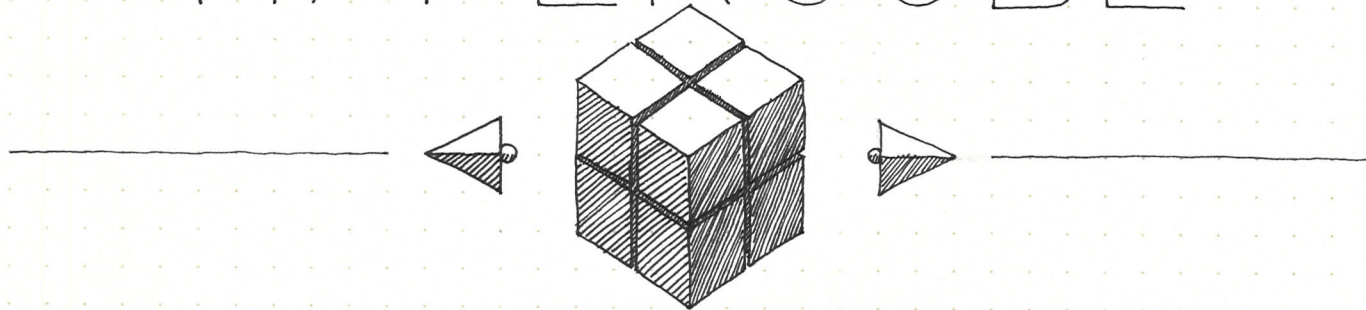


TESTING & LEARNING

# CONVEX SETS

*in the*

# TERNARY HYPERCUBE

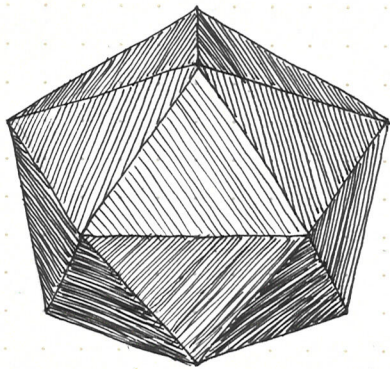


Hadley Black

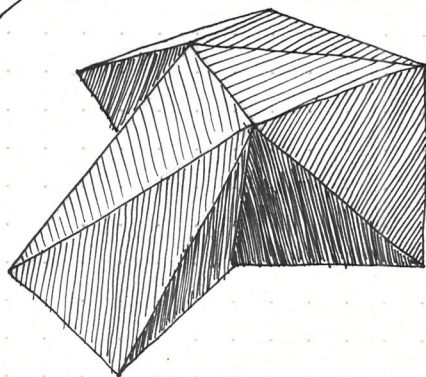
Eric Blais

Nathan Harms

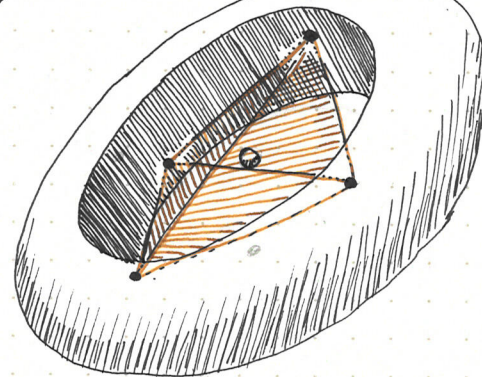
# TESTING CONVEX SETS



Convex



$\epsilon$ -Far from Convex

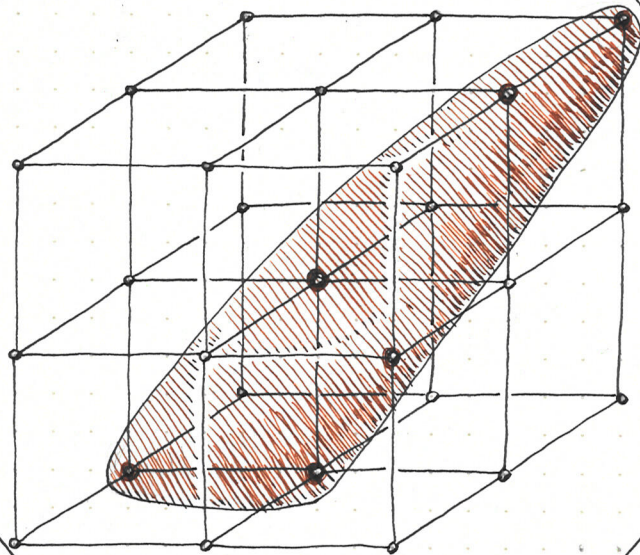
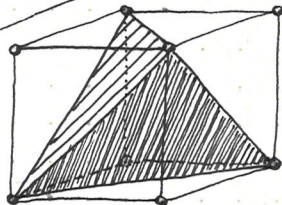


Tight bounds:

- Low dimension [BMR'16  $\times$  3, R'03]
- Gaussian over  $\mathbb{R}^n$  [CFSS'17, KOS'08]
  - ↳ samples only

Unclear how to use queries [BB'20, RV'04]

Discrete convex sets?

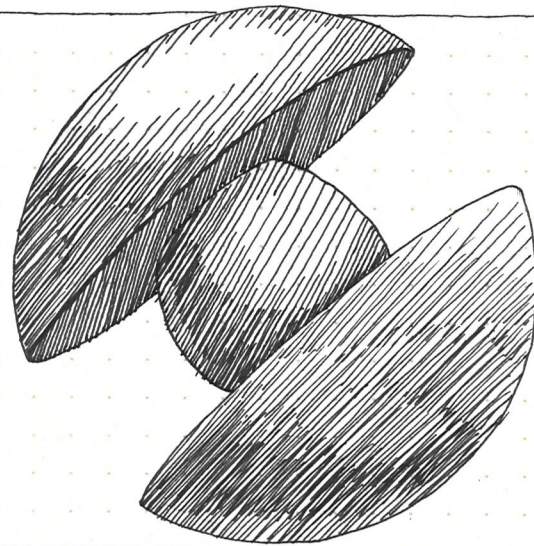
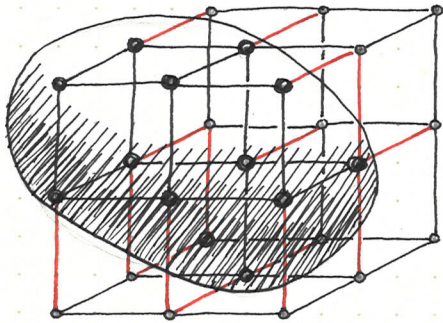


# THEOREMS

## NON-ADAPTIVE TESTING, ONE-SIDED ERROR

• Upper bound:  $3^{\tilde{O}(\sqrt{n})}$

• Lower bound:  $3^{\Omega(\sqrt{n})}$   $\rightsquigarrow$



## EDGE BOUNDARY ( $2n \cdot 3^{n-1}$ edges total)

• Convex sets cut  $\tilde{O}(n^{3/4}) \cdot 3^{n-1}$  edges

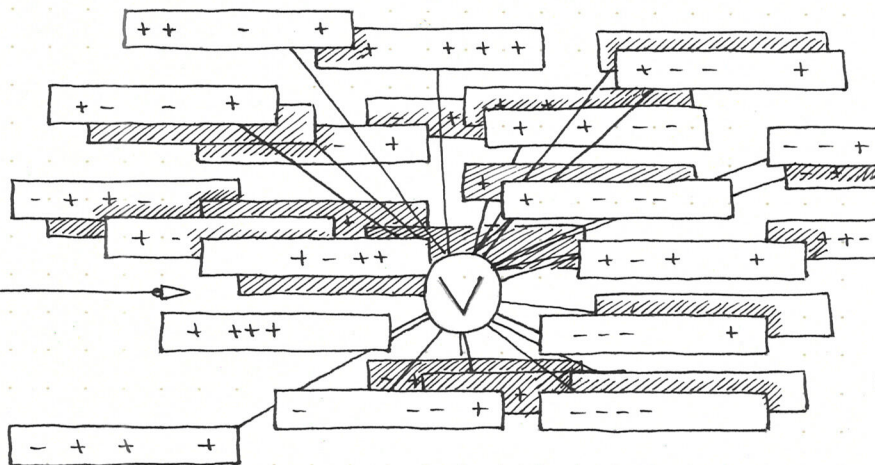
• Convex sets can cut  $\Omega(n^{3/4}) \cdot 3^{n-1}$  edges

## SAMPLE-BASED TESTING & LEARNING

• One-sided error lower bound:  $3^{\Omega(n)}$

• Two-sided error lower bound:  $3^{\Omega(\sqrt{n})}$   $\rightsquigarrow$

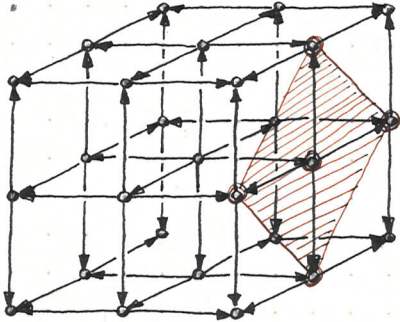
• Two-sided error upper bound:  $3^{\tilde{O}(n^{3/4})}$



Talagrand's random DNFs [BB16, CWX17]

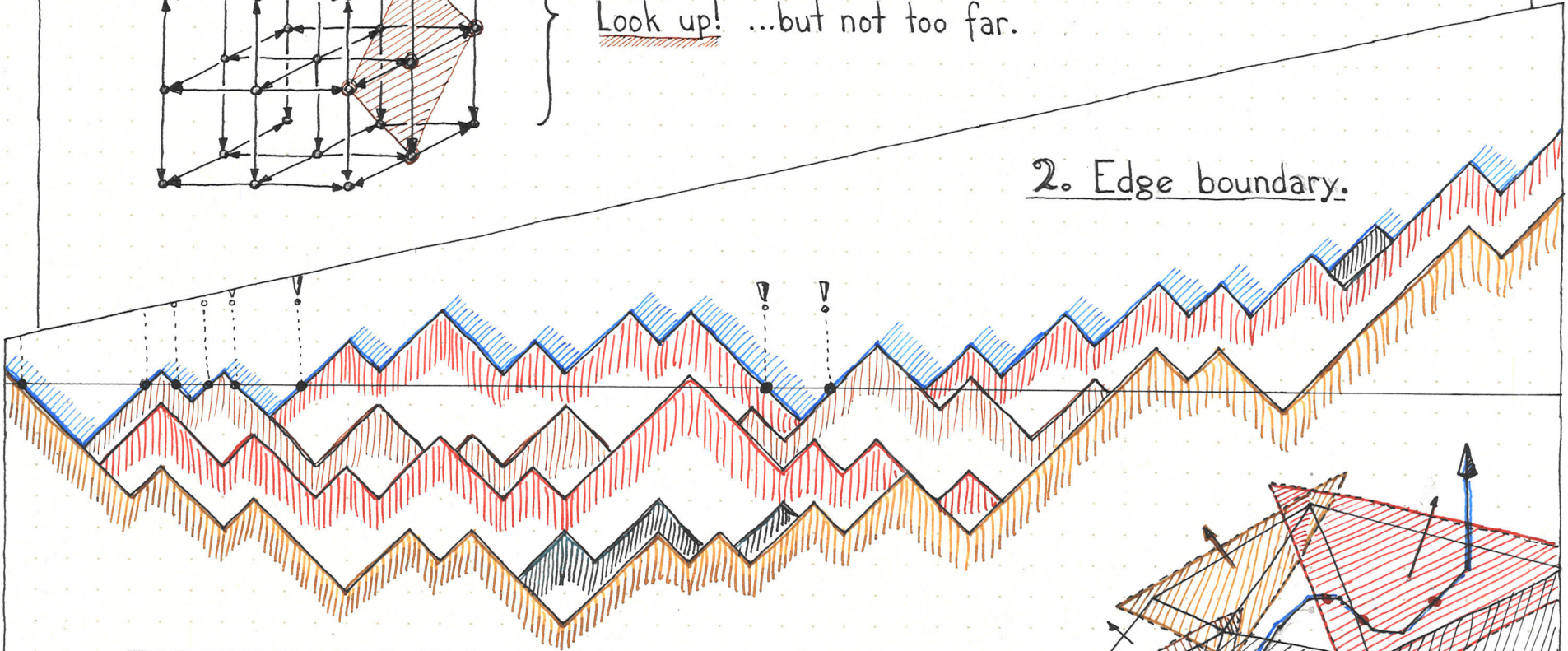
# UPPER BOUNDS

## 1. Non-adaptive testing.



Look up! ...but not too far.

## 2. Edge boundary.



$$E[\# \text{crossings of } m\text{-step } \underline{\text{max-walk}}] = O(\sqrt{m})$$

